

An integrated perspective of the continuum between earthquakes and slow-slip phenomena

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The discovery of slow-slip phenomena has revolutionized our understanding of how faults accommodate relative plate motions. Faults were previously thought to relieve stress either through continuous aseismic sliding, or as earthquakes resulting from instantaneous failure of locked faults. In contrast, slow-slip events proceed so slowly that slip is limited and only low-frequency (or no) seismic waves radiate. We find that slow-slip phenomena are not unique to the depths (tens of kilometres) of subduction zone plate interfaces. They occur on faults in many settings, at numerous scales and owing to various loading processes, including landslides and glaciers. Taken together, the observations indicate that slowly slipping fault surfaces relax most of the accrued stresses through aseismic slip. Aseismic motion can trigger more rapid slip elsewhere on the fault that is sufficiently fast to generate seismic waves. The resulting radiation has characteristics ranging from those indicative of slow but seismic slip, to those typical of earthquakes. The mode of seismic slip depends on the inherent characteristics of the fault, such as the frictional properties. Slow-slip events have previously been classified as a distinct mode of fault slip compared with that seen in earthquakes. We conclude that instead, slip modes span a continuum and are of common occurrence.

Slow-slip phenomena refer to specific deformation modes that are observed seismically or geodetically. The variability of slow-slip phenomena reflects a suite of unique fault-slip characteristics (Fig. 1). When faults slip at sufficiently fast velocities, dynamic forces become significant and seismic waves radiate. The energy carried at wavefronts can overcome frictional forces on locked sections of the fault, resulting in large displacements and 'fast' earthquakes¹. Under some conditions the slip may not reach dynamic velocities, but low-amplitude, low-frequency seismic waves still radiate. These seismic slow signals have only recently been identified, facilitated by networks of high-sensitivity surface and borehole seismometers that record continuously in the frequency band of ~0.001–100 Hz. Among these signals, the most commonly observed are weak continuous vibrations having no clear impulsive phases, known as deep 'non-volcanic' tremor². Tremor often accompanies the aseismic events, with the coupled phenomena named 'episodic tremor and slip' (ETS)³.

A range of other seismic signals indicative of a spectrum of slow source durations and rupture speeds, and limited slip (relative to earthquakes), have been classified as low-frequency earthquakes (LFEs)^{4,5} and very low-frequency earthquakes (VLFs)^{6,7}, with source durations of less than one second and a few tens of seconds, respectively (Figs 1 and 2). These weak seismic events have been observed in Japan², Cascadia³, Central California⁸, Mexico⁹ and Costa Rica¹⁰ (Fig. 3). In several regions where tremor signals are well recorded, a significant fraction of the tremor signal seems to comprise superposed LFE waveforms^{10,11}. This implies that tremor represents the chatter from tiny, distributed sources that radiate randomly. VLFs are found buried in tremor signals, further suggesting that occasionally LFEs coalesce into an organized rupture that radiates seismic waves at a lower frequency^{12,13}.

Aseismic signals reflect fault slip so slow that inertial forces and seismic radiation are negligible. The occurrence of such 'quasi-static' slow slip has been known for many years (for example, ref. 14), but its significance along plate boundaries was not recognized until

plate-boundary-scale GPS networks became operational in continuous mode ~15 years ago^{15–17}. Less abundant strainmeters and tiltmeters also measure aseismic transients, and with much greater resolution than GPS¹⁸.

The pervasiveness of slow-slip phenomena in plate boundary regions, the spontaneity and regularity with which they sometimes occur, and some of the seismic signals they emit are new and exciting. However, some of the phenomena have been documented for decades. Early seismological studies have shown that some earthquakes are relatively depleted of high frequencies¹⁹, reflecting source durations longer than expected from standard relationships²⁰. These include slow, mostly shallow earthquakes on oceanic transform faults^{19,21} and in shallow sediments²², tsunami earthquakes²³ and glacial earthquakes²⁴.

Slow-slip phenomena have also been documented in the context of other, more familiar types of fault slip. Examples include aftershocks and afterslip, repeating earthquakes and creep, swarms and various types of aseismic deformation. Although driven by gravity instead of stresses resulting from relative plate motions, glaciers and landslides also share many commonalities with slow slip of tectonic origins.

Slow-slip phenomena along tectonic plate boundary faults

When and where. The sources of the slow geodetic signals are generally consistent with shear slip on the plate interface^{16,25} (Fig. 2). The locations of the slipping surface and the interface generally have uncertainties of several kilometres or more. Plate interfaces have been mapped using seismic imaging techniques, potential field methods, and high-resolution locations of earthquakes^{26,27}.

The most well-constrained sources of seismic slow slip (LFEs) and plate boundary locations come from the Nankai subduction zone in southwest Japan. Here, the slow-slip sources coincide with the plate boundary²⁶. LFE sources in the Cascadia subduction zone²⁸ and along the San Andreas fault (SAF)²⁹ system

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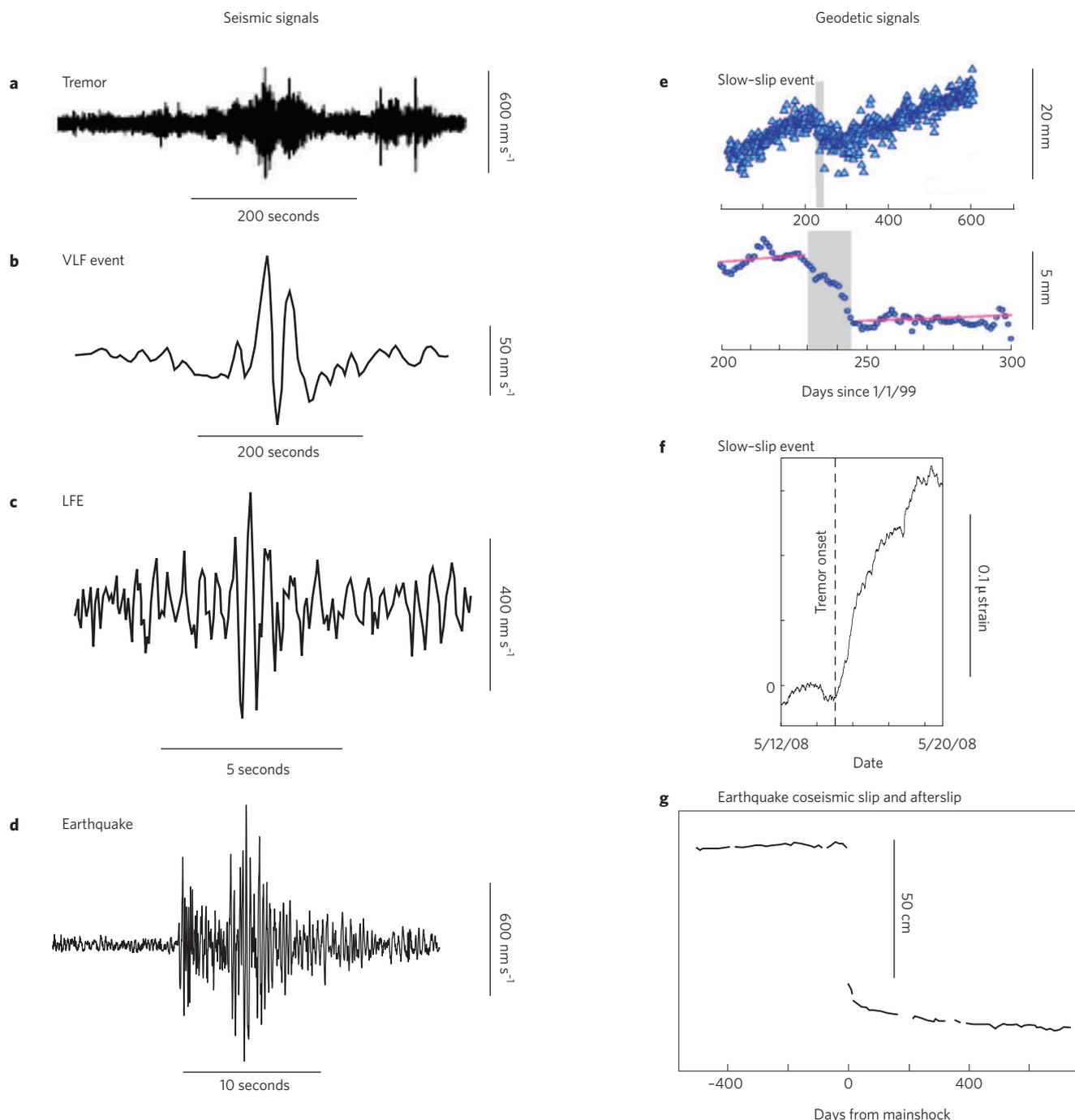


Figure 1 | Illustrative examples of slow-slip signals. a, Tremor and **b**, VLF from Japan, filtered between 2–8 and 0.005–0.05 Hz, respectively. **c**, LFE from Japan. **d**, M1.9 earthquake in western Washington. **e**, Top: daily GPS E–W displacements measured on Vancouver Island. Bottom: averaged and detrended GPS data (pink lines show the fit trend) reveal a slow-slip event (shaded). **f**, Slow slip in differential shear strain measured in western Washington. Strain transient onset coincides with increased tremor activity. **g**, GPS N 55° displacement -100 km from the 2001 M8.4 Peru earthquake. The large offset reflects the coseismic slip and the subsequent decaying deformation may be afterslip⁹⁹. Figures reproduced with permission from: **a,b** ref. 77, © 2008 GRL; **c**, ref. 5, © 2006 NPG; **e**, ref. 16, © 2001 AAAS; **f**, ref. 98, © 2008 AGU; **g**, ref. 99, © 2005 JGR.

transform boundary locate on the respective plate interfaces. A geographically broader study of LFEs in the subduction zones of Japan, Costa Rica and Cascadia also places sources on the plate interface, but samples only three-hour time windows¹⁰. Slip vectors estimated from LFEs and VLFs in Japan indicate slip along the plate interface in the convergence direction^{13,30}.

In Cascadia, quasi-static slip of several centimetres on the plate interface has been inferred directly down-dip from the locked zone of the plate interface, between the 25- and 45-km-depth contours¹⁶.

However, the non-uniqueness of the modelled solutions also permits slip zones at different depths or shear distributed over a depth range of more than 10 km (ref. 31). In much of Cascadia, tremor sources are consistent with origins on the plate interface^{10,28}, but their distribution beneath Vancouver Island extends from the plate interface to near the surface with the densest concentration being well above the interface^{31,32}.

The durations of aseismic-slip events in numerous subduction zones range from days to years, with magnitudes of displacement

of up to several tens of centimetres^{31,33}. In Japan and Cascadia these events occur quasi-periodically, with periods of ~3 to ~19 months that vary along each subduction zone^{3,25,34,35}. Elsewhere, for example Alaska, Mexico, New Zealand and Costa Rica, slow-slip events sometimes recur but with no apparent regularity^{17,36,37}.

Quasi-static-slip events are accompanied by a variety of seismic phenomena. In many regions where aseismic slip occurs beneath the locked zone, for example Cascadia and southwest Japan, tremor always accompanies quasi-static slip. However, the converse is not true, for the reasons noted below^{3,25,38}. A few studies in Japan note that aseismic slip begins before the onset of tremor activity and, in some places, occurs without any detectable seismic signals^{39,40}.

Aseismic slip at shallow depths has correlative seismic signals that have spectral and scaling characteristics more typical of ordinary 'fast' earthquakes. Examples include regions just downdip of the shallow slow-slipping zones of the subduction zones of northern New Zealand⁴¹ and the Boso peninsula, Japan⁴². Shallow quasi-static slip accompanied by increased rates of regular earthquakes has also been observed along the creeping section of the SAF¹⁴ and the south flank of the Kilauea volcano, Hawaii⁴³. The coupled earthquakes locate where ambient seismicity occurs, beneath the zone of quasi-static slip.

Seismic slow-slip signals observed without geodetic counterparts, such as along the SAF^{29,44,45} and in the subduction zones noted above, plausibly can be attributed to detection differences between geodetic and seismic instrumentation. Such differences between regions may explain some apparent regional variations in slow-slip phenomena. Surface GPS instruments are sensitive only to quasi-static-slip events below ~25 km depth with magnitude (M) > 6, whereas small M 5–6 events can be detected only by borehole tiltmeters in Japan²⁵. Even with borehole strainmeters, M ~5 slow-slip events could go undetected if at depths below ~15 km⁴⁵. The observation of tremor both during ETS events and between them suggests that quasi-static slip may often occur between such events but go undetected^{40,46}. On the other hand, deep ETS events have been measured in southwest Japan⁴⁷, but have not been observed directly in northeast Japan, yet both regions contain equally dense seismic and geodetic instrumentation.

Shear slip on frictional, pressurized, near-failure faults. Numerous lines of evidence strongly suggest that slow-slip phenomena result from shear slip on faults near failure with low effective confining pressure, most probably owing to near-lithostatic fluid pressures. Tremor in a wide range of tectonic environments can be instantaneously triggered by transient stresses on the order of a few to tens of kilopascals, imparted by surface waves of regional and teleseismic events^{44,48–51} (Fig. 4). Static-stress changes on the order of a few kilopascals from neighbouring earthquakes also trigger changes in rates of tremor⁵² and LFEs²⁹ along the SAF. Furthermore, tremor activity seems to be modulated by the Earth's tidal deformation^{53–55}, with tidally induced fault-parallel shear stresses correlating best with the tremor activity⁵⁶. Correlations between slow-slip phenomena and stress perturbations on the order of a few kilopascals from atmospheric⁵⁷ and other climatic-driven events^{58,59} also indicate that participating faults are critically stressed.

It is generally agreed that near-lithostatic fluid pressure reduces the effective stresses and makes slow-slip events highly sensitive to external stress perturbations. Evidence of elevated fluid pressures comes from tomographic imaging of elastic properties around the source region of the slow-slip phenomena^{5,27,60–62}. These studies show that tremor and aseismic slip occur preferentially in regions with high ratios of compressional- to shear-wave seismic velocity, anomalously high Poisson's ratios, or ultralow shear-velocity layers. These all indicate that fluids are widely present, with pore pressures near lithostatic values (Fig. 2). Fluids may come from dehydration of hydrous minerals in the subducting sediments and oceanic crust⁶³,

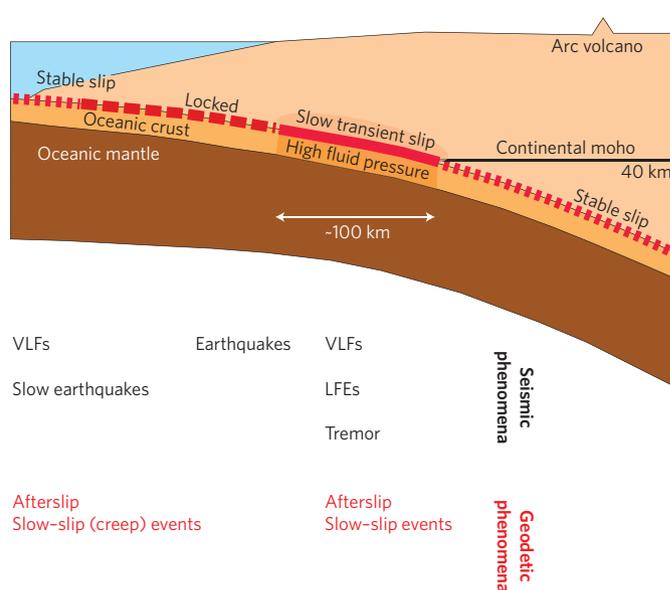


Figure 2 | Schematic cross-section of the Cascadia subduction zone. The various slip modes believed to occur along the plate interface are noted (red lines) with the corresponding observed phenomena indicative of each listed below. In Cascadia and elsewhere much evidence suggests that high fluid pressures exist in the region where slow-slip phenomena occur. Modified from ref. 61, © 2009 NPG, ref. 5, © 2006 NPG and ref. 62, © 2009 AAAS.

becoming sealed in and pressurized where the plate boundary has low permeability^{27,61}. The presence and source of fluids in the lower crust near strike-slip faults such as the SAF are still speculative, although recent seismic imaging studies have revealed conductive properties at the base of the crust⁶⁴.

Physical models of slow-slip phenomena. The macroscopic behaviours of plate boundary faults under the stresses caused by relative plate motions are typically described in terms of frictional properties⁶⁵. Thus, most models of aseismic slow-slip events appeal to shear slip on frictional faults^{5,30,50}. Figure 2 illustrates the broad variation in frictional properties that are ascribed to subduction zones, but applicable to several plate boundary zones. The same picture can be drawn for transform boundaries by simply plotting the interface vertically⁶⁶. Frictional models explain the occurrence of quasi-static-slip events with rates and displacement values consistent with observations^{67–71}, although the physics assumed in these models may differ. Moreover, they seem to require low confining stresses and, in some models, significant involvement of fluid-pressure processes⁷¹, consistent with the aforementioned inferences.

Other explanatory models involve fluids, either exclusively through mechanisms such as hydraulic fracturing or permeability pumping^{2,32}, or in combination with frictional processes^{49,70,71}. An intriguing example of the latter involves dilatant strengthening. Here, frictional faults dilate as they accelerate towards dynamic failure at rates that prohibit draining, such that pore pressures drop. This raises the effective normal stress and thus limits or quenches dynamic rupture^{70,71}. The lack of phase lag between seismic waves and tidal forces, the tremor and slip rates they modulate, and high tremor-migration rates (as high as 5–45 km hr⁻¹ (ref. 11), in excess of plausible fluid-diffusion rates) imply that changing fluid pressures cannot involve diffusion or flow⁷².

A primary role for quasi-static slip. The earliest ETS observations clearly demonstrated the coupled nature of seismic and aseismic slow-slip events³. Corroborative subsequent studies have led to

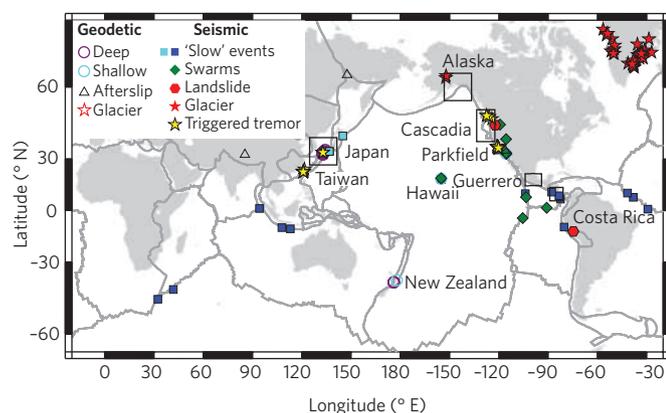


Figure 3 | Location map of seismically and geodetically observed slow-slip phenomena. Regions where ETS events have been observed are marked by black boxes. Modified from ref. 47, © 2007 AGU and ref. 100, © 2010 Springer. The locations of some slow-slip phenomena for which measurements of duration and moment have been made and plotted in Fig. 5 are shown with the same symbols (see Supplementary Table 1). The yellow stars mark the locations of tremor triggered by regional and teleseismic earthquakes^{44,48–51}.

proposals that tremor could be used as a proxy to monitor aseismic slip^{29,38,73}. As well as the broadscale temporal and spatial coincidence of seismic (tremor, LFE and VLF) and quasi-static-slip sources within tens of kilometres and days, in Cascadia and Japan both also show clear along-strike migrations that track each other, at speeds on the order of a few tens of kilometres per day^{12,46}. These correlations warrant exploration of a causal connection between the seismic and aseismic phenomena. ‘Causal’ in this context refers both to the processes that load or supply the strain energy fuelling the eventual fault slip, and those that may initiate (trigger) a slip event early. The relative timing and moments of seismic and aseismic slow slip provide key constraints on the driving and triggering processes. The moment measures the potency of a slip episode to relax accrued stresses, and is proportional to the product of the slipping area and the distance slipped⁷⁴.

Although resolvable in only a few cases, the fact that the onset of aseismic slip precedes the start of the seismic activity in Hawaii⁴³ and Japan^{39,40} means the seismic slip does not trigger the quasi-static slip. However, the reverse may be inferred. We also conclude that the seismic slip is not causal in the sense of providing the energy that drives the aseismic slip, because when measurable, the relative moment of the cumulative seismic activity is orders of magnitude smaller than that of the aseismic slip (Fig. 5). In Japan, aseismic-slip events near the Boso peninsula region have moments that significantly exceed those of the earthquakes that accompany them⁴². In the Nankai region the rate of seismic moment released from detectable VLF sources was 0.1% of the rates from adjacent, contemporary slow-slip events¹³. In Cascadia, for each of eight ETS episodes the moment of the aseismic slip exceeds that of the cumulative tremor by more than a factor of a million⁷⁵. Tremor represents only the energy radiated above ~1 Hz, thus the latter probably underestimates the total seismic moment. Indeed, coherent seismic waveforms with energy at frequencies as low as 0.002 Hz have been observed in association with aseismic-slip events, but always in the tremor signals^{12,76}. This demonstrates the detectability of such low-frequency radiation and shows that biases in band-limited estimates of seismic moment are probably too small to account for their much smaller values relative to aseismic moments.

Thus, we conclude that quasi-static slip is the primary mode in which the accrued tectonic stresses are relieved. The observations

do not distinguish between the seismic slip also being tectonically driven or relaxing stresses redistributed as a result of the aseismic slip. Although uncertain, the possible balance between the cumulative aseismic slip over complete ETS cycles and that accrued owing to plate motion in Cascadia would argue in favour of the first proposition^{46,77}.

Slip-mode stationarity. We suggest that the specific slip mode at a particular location is an inherent property of the fault, rather than being determined by transient conditions (for example, the causative load itself, or fluid flow). The observation of only a single mode of slip at a given locale for the duration of our observational window of several decades supports this inference, and further implies that the properties governing the slip mode are stationary on this timescale. Corroborative observations include spatially anticorrelated distributions of earthquakes and slow-slip sources, observed for both large and small earthquakes. Sources of slow quasi-static slip in Alaska about the rupture zone of the great *M*9.2 Alaska earthquake⁷⁸ of 1964. In Japan, slow-slip sources occur on the edges of the rupture planes of the *M*7.9 Kanto earthquake⁴² of 1923 and just below the *M*7.9 Tonankai 1944 and *M*8.0 Nankai 1946 earthquakes⁷⁹. In Cascadia, the locations of tremor sources are anticorrelated with the section of the plate interface inferred from palaeoseismic data to have slipped during past megathrust earthquakes⁷⁶ and, curiously, also with earthquakes in the crust of the overriding plate³¹.

The maxima of seismic and aseismic slow-slip source distributions also seem to locate in spatially adjacent, but not coincident, regions. The most recent estimates of tremor and quasi-static slow slip from Japan show the two migrating in temporal sync with one another, but with a bimodal tremor distribution that has peaks outlining the slower slip rather than being coincident with it⁸⁰. Tremor source distributions mapped in the subduction zone regions of Mexico, Alaska and Cascadia all peak down-dip of the greatest quasi-static slip^{31,36,62}.

Conditions for slow-slip phenomena. Although the mode of slip seems to be stationary, the requirements for triggering slip vary temporally and are not easily satisfied. Recent systematic surveys of tremor in California^{44,48} and Taiwan⁵¹, triggered by the seismic waves from distant earthquakes, revealed that triggered tremor occurs in only a few isolated regions, the locations of which varied for different triggering earthquakes.

The particular conditions required for slow slip have become apparent as more regions have been studied. Thermal controls were initially thought to be key⁴⁷ because ETS was first identified in the relatively young and warm subducted crusts of Cascadia and southwest Japan, and were absent in northeast Japan where the predicted pressure–temperature paths are much cooler⁶³. However, detailed finite-element thermal modelling of the Cascadia and southwest Japan subduction zones now shows quite different pressure–temperature paths in each region at depths where ETS is observed, suggesting that ETS does not require a specific temperature or metamorphic reaction⁸¹. Furthermore, tremor and slow-slip events have been recently observed in relatively old and cold subducting crust in Costa Rica¹⁰ and Alaska³⁶. Hence new hypotheses invoking differences in frictional or permeability properties have been proposed to explain the lack of ETS in northeast Japan^{47,63}. However, more work is required to fully test these hypotheses.

Slow-slip phenomena in a larger context

Coupled seismic- and aseismic-slip events on natural surfaces have been observed in many contexts, some fairly familiar and well studied. As just noted in the context of the newly discovered plate boundary phenomena, investigations in many

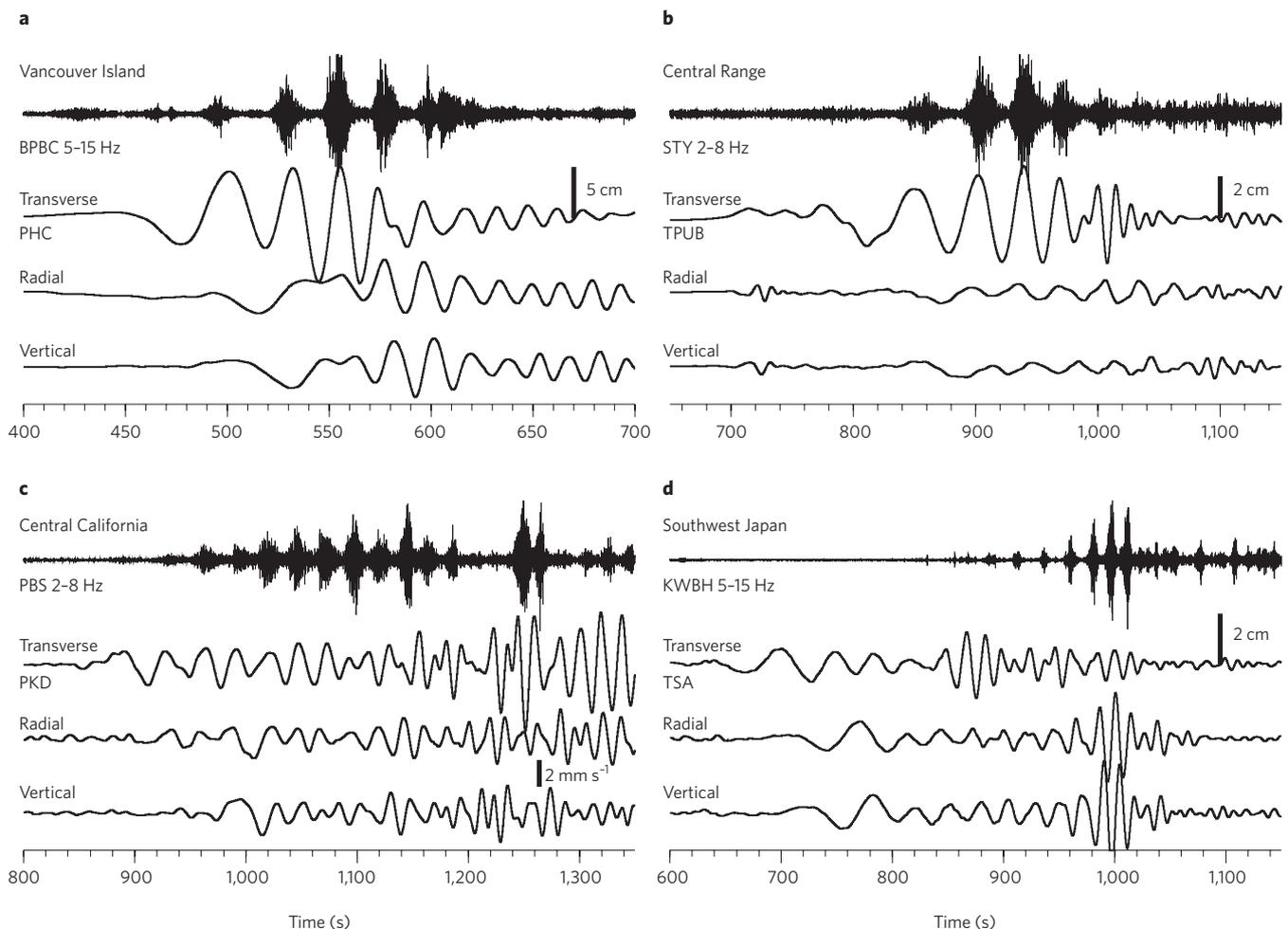


Figure 4 | Examples of triggering seismic waves and triggered tremor. A comparison of surface waves of large teleseismic earthquakes and triggered tremor beneath **a**, Vancouver Island in British Columbia, **b**, the Central Range in Taiwan, **c**, the SAF in Central California and **d**, the subduction zone in southwest Japan. The station and component names and the frequency ranges of the applied filters are marked on the left-hand side of the traces. The traces have been time-shifted to reflect the relationship between the surface waves and tremor at the source region. Figures reproduced with permission from: **a**, ref. 50, © 2007 NPG; **b**, ref. 51, © 2008 GJI; **c**, ref. 44, © 2009 GJI; **d**, ref. 49, © 2008 EPS.

settings are required to learn which factors are most relevant and provide opportunities to fill in observational gaps that arise from instrumental limitations in individual settings. We identify at least five hallmark characteristics of slow-slip phenomena: (1) the ratios of slip to slipped area are low and durations are long, relative to 'fast' earthquakes; (2) accrued stresses are relaxed dominantly through quasi-static slip that triggers a seismic response, evident in aseismic slip that precedes the seismic activity and has greater moment. The seismic response is sometimes quenched before reaching fully dynamic speeds, as in tremor, LFEs and VLFs; (3) explanatory models invoke shear slip on faults with frictional properties transitional between those that result in continuous creep and those that are fully locked, punctuated by nearly instantaneous slip (stick-slip); (4) near-failure conditions probably reflect low confining stresses. Fluids at high pressure remain the most viable way to achieve these conditions, and may play important roles in quenching slip and in the recurrence of slow-slip events; (5) local, stationary properties determine the dominant slip mode.

Afterslip and aftershocks. Afterslip represents transient quasi-static slip triggered by the rapid stress release in a mainshock, which is typically followed by increased seismic activity known as 'aftershocks'. The underlying mechanism of aftershock generation is

still debated⁸². A linear relationship between postseismic geodetic deformation, modelled as slow slip on the mainshock fault, and the cumulative number of aftershocks has led to suggestions that aftershocks may be driven primarily by afterslip^{83–85}. These coupled seismic and aseismic processes exhibit almost all of the aforementioned hallmark characteristics of slow-slip phenomena: (1) the durations of the aseismic slip and aftershock sequences may last for days to months; (2) the afterslip moment exceeds the aggregate moment of aftershocks by more than two orders of magnitude (Fig. 5)^{85,86}; (3) frictional models akin to those applied to tectonically driven plate boundary slow slip explain not only the temporal decay of aftershocks and afterslip, but also their spatial migration^{87,88}; (4) anti-correlated coseismic- and postseismic-slip distributions suggest that afterslip fills in gaps in slip remaining after a mainshock⁸⁴.

Aseismic deformation and earthquake swarms. Sometimes sequences of clustered earthquakes strike in a short period of time with no obvious mainshock. The driving forces for these 'earthquake swarms' may be aseismic slip (measured in just a few cases), fluid, or magma migrations^{43,72,89,90}. Swarms share several key features with plate boundary slow-slip phenomena⁷²: (1) durations of swarm activity and aseismic slip last days to months; (2) the aggregate seismic moment is only a small fraction of the cumulative

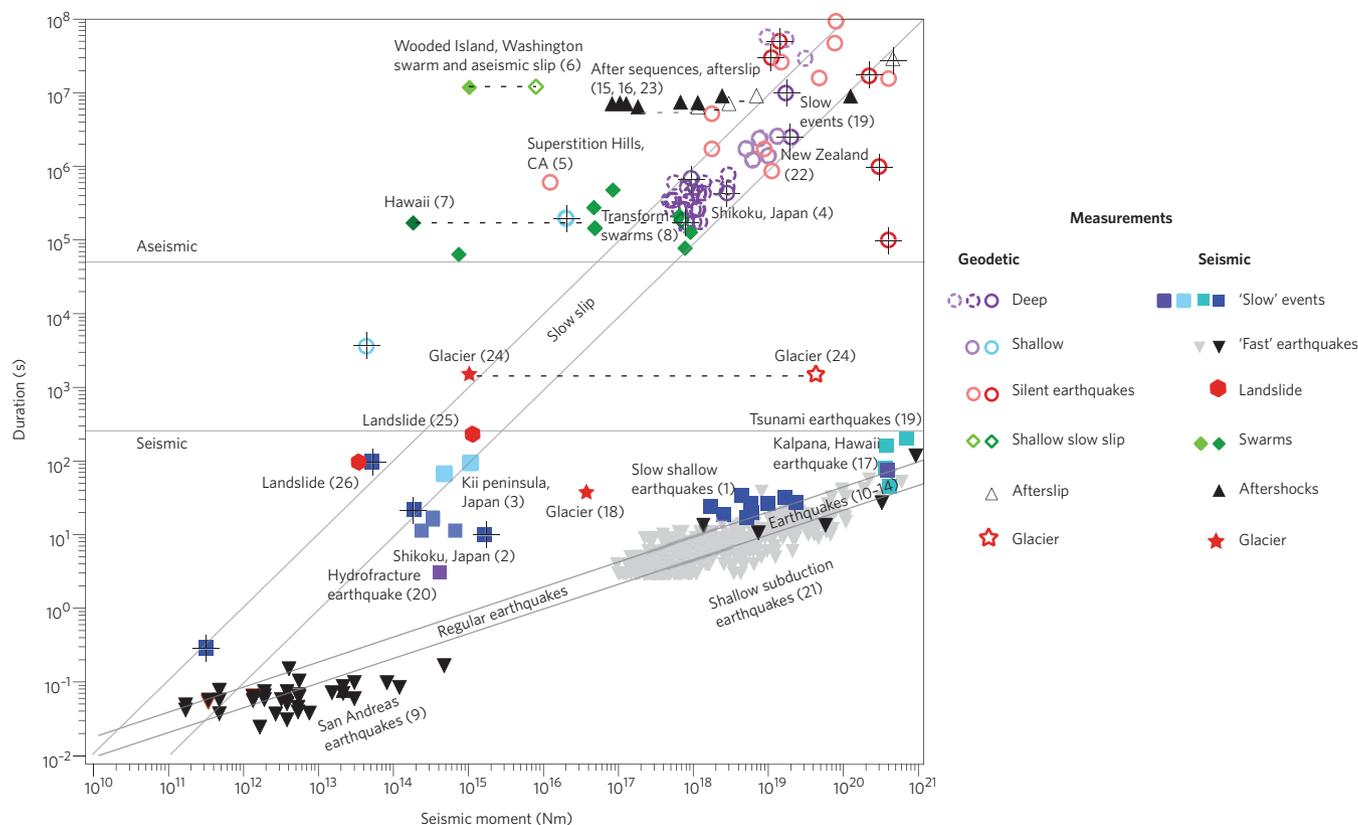


Figure 5 | Seismic moment versus source duration for a variety of fault-slip observations. Augmented version from ref. 96, © 2007 NPG, which infers two distinct scalings between moment and duration (diagonal bands). Open and filled symbols denote geodetic and seismic measurements, respectively. Measurements from ref. 96 have plus signs on the symbols, and all others are cross-referenced to sources listed in Supplementary Table S1. ‘Fast earthquakes’ and ‘shallow subduction earthquakes’ are too numerous to list but are listed in Supplementary Table S1. Data from the former come from only two sources. Dashed horizontal lines connect related geodetic and seismic data. Solid horizontal lines highlight the gap between seismic and geodetic durations.

aseismic moment⁹⁰ (Fig. 5) and some swarm events migrate at rates of kilometres per hour, consistent with the propagation of slow-slip events⁷²; (3) the magnitudes of swarm earthquakes tend to be small and irregularly distributed in a sequence, reminiscent of tremor activity; (4) pressurized fluids are often invoked in explanations of swarms in magmatic and geothermal environments; (5) in the case of Hawaiian swarms, the earthquakes occurred in the same region as background seismicity⁴³.

Steady and transient fault creep and repeating earthquakes.

Sections of the SAF⁹¹ and other principal plate boundary faults around the globe⁴² are known to creep steadily or exhibit transient aseismic slip. These often have associated seismic activity. ‘Repeating earthquakes’ are one example and probably represent repeated seismic failure of a single strongly coupled spot loaded by aseismic creep on the surrounding fault plane⁹¹. Other sections of the SAF are characterized by occasional transient aseismic-slip events, some of which are accompanied by increased seismicity rates¹⁴, and others without any seismic response⁹². These coupled aseismic and seismic phenomena share the aforementioned distinguishing characteristics: (1) the transient aseismic slip lasts days to weeks^{14,92}; (2) the aggregate moment release from the triggered earthquakes is negligible compared with that from the slow-slip events¹⁴; (3) although the materials and conditions may differ, the same frictional models and input parameters invoked to explain deeper plate boundary slow slip have been applied to explain shallow, steady and transient slip⁸⁷; (4) high pore pressures are inferred to be responsible for the creep and transient

slip⁹²; (5) triggered earthquakes occur in the same regions as ambient seismicity¹⁴.

Gravity-driven aseismic and seismic slip.

Landslides and glaciers occur on natural surfaces that move and exhibit many of the same behaviours as tectonic faults, including coupled seismic and aseismic slip: (1) slip is sufficiently slow that even the seismic radiation may have characteristics typical of slow tectonic events; (2) although simultaneous geodetic and seismic measurements have been made in only a few glacier studies, results indicate that the aseismic slip triggers the seismic motion and is the primary mode of relaxing the stored gravitational energy. A slip event on an Antarctic glacier has a geodetic moment that exceeds the seismic moment by orders of magnitude (Fig. 5), and the arrival time of the first seismic energy, corrected for the source-receiver travel time, lags the onset of geodetically estimated slip by 20–150 seconds⁹³; (3) glacial quakes in Antarctica, Alaska and Greenland have been interpreted as frictional stick-slip behaviour at the base of ice masses²⁴. A more detailed geodetic and seismic study of an Antarctic glacier infers dynamic slip on frictionally strong spots that radiate on an otherwise quasi-statically sliding basal surface⁹³; (4) pore-pressure evolution plays a significant role both in landslide and glacier movements. Theoretical models of landslide movement by stable and stick-slip sliding involve coupled frictional and pore-pressure diffusion processes⁹⁴. Correlations between landslide velocities and diurnal changes in atmospheric pressure have been attributed to pore-pressure-diffusion processes that modulate basal pore pressure and thus the shear strength and velocity⁹⁵. Weakening resulting

from pore-pressure changes associated with seasonal variations in water availability has been postulated to be responsible for a greater rate of glacial quakes during the summer months in Greenland²⁴.

A continuum of slip modes?

The fault surface we propose primarily slips quasi-statically, such that the amplitude and rate of slip are limited, perhaps because the fault surfaces are inherently weak or the failure process becomes quenched. This slow slip probably involves intermediate frictional processes between stick-slip behaviour and steady creep that result in the nucleation of failure or slip, and other processes involving fluid pressures that may quench the acceleration of slip (for example, dilatant hardening). Scattered on or near this fault surface are tiny fault patches that may accelerate to dynamic or near-dynamic rupture velocities and radiate seismic waves.

The time required for slip events of particular efficacy to completely release accrued stresses can be quantified in terms of the scaling between duration and moment. This scaling is diagnostic of the underlying mechanics. We hypothesize that slip modes observed in nature should span a continuum, given the heterogeneity and complexity of natural systems, rather than separating neatly into distinct fast or slow groups, as has been suggested¹⁶. We test this hypothesis by augmenting the plot of moment versus duration observations that led to the latter conclusion, with measurements from the broader range of sources described herein (Fig. 5). We plot the aggregate durations and moments for aftershock and swarm sequences as proxies for aseismic slip, noting that the aseismic moments are likely to be much larger and thus would be within the distribution of the other slow geodetic measurements. The few swarms and aftershock sequences for which both seismic and geodetic observations (connected by dashed lines) exist support this assumption.

The augmented scaling data suggest a more careful consideration of the existence of two distinct failure modes — fast and slow. Two distributions clearly exist in the data, but we suggest that they are observational, comprising either geodetic or seismic measurements. These are separated by a gap in duration of more than two orders of magnitude (Fig. 5, horizontal lines). This gap may be attributed partly to instrumental limitations¹⁸. It is reasonable to question whether the slow-scaling relation originally inferred even fits this larger dataset, as well as the validity of fitting a single line to widely separated clusters of data. We suggest that as more data are added, the lines separating slow- and fast-slip events will blur even more, indicating a continuum of slip modes.

Measurements of earthquakes and slow-slip events from a broad range of global settings are found to overlap with measurements of slow-slip events at plate boundary settings (Fig. 5). This overlap implies that the recently discovered slow-slip phenomena, generated at plate boundaries as a result of tectonic processes, are not so extraordinary. Furthermore, we suggest that a continuum of slip modes exists, rather than the distinct separation between slow slip and earthquakes. The mode of slip is determined by the inherent properties of the fault surface. Studies of slow-slip phenomena, viewed from a global, integrated perspective, are leading to a more complete picture of how faults slip and release tectonic stresses. Such an integrated perspective is critical for evaluating the hazards posed by earthquakes and other natural systems involving catastrophic slip. For example, it has been suggested that slow-slip phenomena could be used to delineate the up-dip and down-dip limits of the seismogenic zone that ruptures in megathrust earthquakes⁷⁶. Slow slip also imparts stress changes on nearby locked faults and may act as a trigger for large earthquakes, although robust observations of this process are rare⁹⁷. The strong sensitivity of slow-slip phenomena to stress perturbations suggests that they could serve as natural 'stress meters' to monitor fault zones during large earthquake cycles.

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Author contributions

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Additional information

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